

The software module MDPP-16-QDC provides the functionality of a fast charge integrating ADC , a CFD+TDC and a pulse shape discrimination unit. It also works with short pulses of plastic scintillators and provides neutron/gamma pulse shape discrimination with liquid scintillators

## MDPP-16 with QDC software module:

- **Gain-polarity jumpers**  
determine: termination, polarity, input range and input configuration (differential / unipolar).  
Special QDC jumpers available to get best amplitude resolution for plastic scintillators.
- **Low noise variable gain input amplifiers.**  
Input signals for maximum range (highest spectrum channel)  
**Plastic scintillators** pulse width 5ns (QDC jumpers 2V):  
200mV to 5V (20pC to 500pC)  
**LYSO**, Pulse width 30ns (any input jumper possible)  
15mV to 3V (10pC to 1.5nC) (other jumpers on request)
- **Timing resolution**  
down to 60ps channel to channel resolution,  
CFD timing, TF integration / differentiation time down to 25ns
- **Pulse shape discrimination**  
delivers two amplitudes: one is the standard integrated pulse amplitude (integration time 25ns to 1.6us), the second is a short integration of the rising edge of pulse. Integration as short as 12.5 ns to 350 ns. This is fast enough to give good neutron / gamma separation for liquid scintillators  
Also works for Stilbene, CLYC.
- **AC-coupled and baseline restored**  
Offsets of the input signals have no effect. Even at highest rates, the amplitude keeps stable.
- **Dead time / rate capability**  
Channel dead time is 390ns, (integration time up to 300ns included). For longer integration time dead time is integration time + 100ns.
- **Two high resolution monitor outputs**  
for monitoring input signals and integrals of signals.
- **Two high resolution trigger inputs**  
24 ps resolution, start window, add time stamp
- **One high resolution trigger output** (1.5 ns resolution)
- **Installation and update via USB**

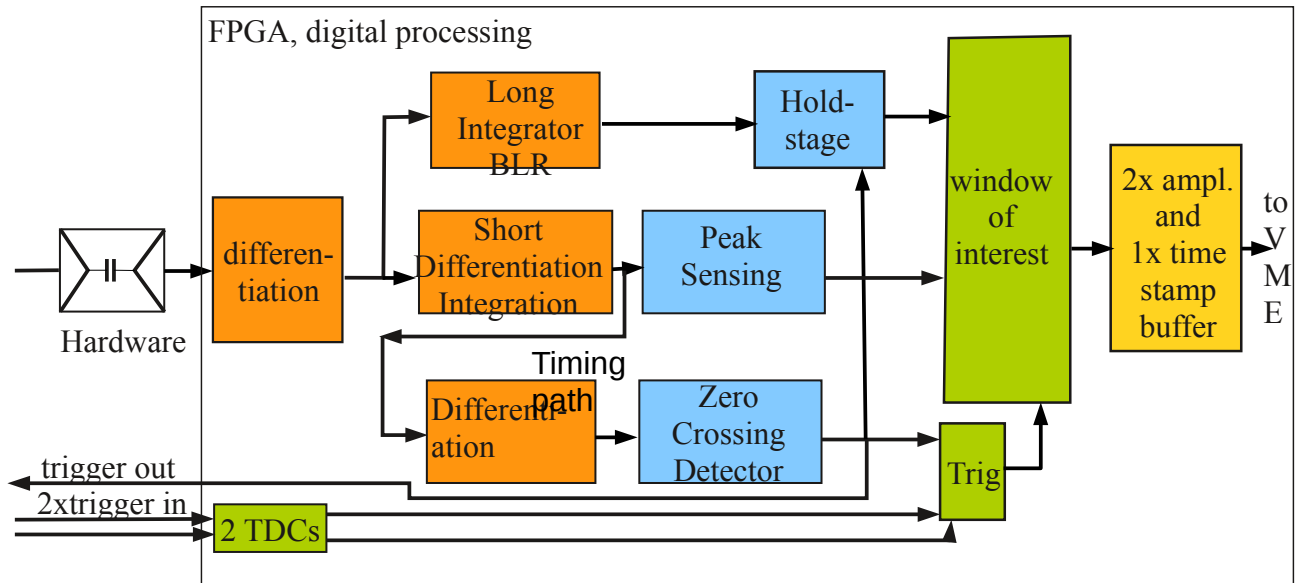


## Software module: "QDC"

Delivers timing and amplitude and pulse shape analysis for signals from fast charge amplifying Detectors. For Example Photo multipliers, GEM, Channel plate..

Replaces Fast amplifier, CFD, QDC, TDC.

The following picture shows a schematic representation of the software:



The signal is amplified filtered digitized. Then it is split into three branches: timing branch, short integration and long integration. The timing branch takes the shaped signal from short integration branch. It consists of a **differentiation stage**, which differentiates and the signal with a short time constant. Then a digital **Zero crossing detector** calculates an amplitude independent time trigger (=time stamp).

In the "short integration" branch the signal is differentiated with a time constant down to 12.5ns. This allows to extract a very short time interval at the beginning of the pulse, which even allows to perform pulse shape discrimination with liquid scintillators.

The "long integration" path is the QDC-(Charge to digital converter) part of the processing software. Usually the full input pulse is integrated here. Integration times of 25 ns to 6400 ns are possible. As the input is AC-coupled a baseline restorer is required, to preserve a stable pulse amplitude at very high rates. The integrated signal is sampled at a well de-

finied time, determined by the timing branch.

Then the two amplitude and timing values are filtered by a **window of interest** and stored in a **buffer**.

### Short data:

- Amplitude resolution of up to 16 k
- Trigger to channel time resolution of < 75 ps rms, uniform at any delay.
- Channel to channel time resolution of < 75 ps rms, uniform at any delay.
- Trigger input with 24 ps timing resolution
- Can be operated self triggered or externally triggered
- Outputs internal raw trigger with 1.5 ns time resolution

As easy to operate as all mesytec modules and fully data compatible.

charge pulse as it is produced by a liquid scintillator when detecting a neutron interaction.

**Only 8 parameters have to be set:**

**In Hardware:**

**Polarity** of the signal,  
set Jumper to correct position

**Register Settings**

**Signal properties:**

1. signal width [ns]
2. maximum signal amplitude [mV]

**Analysis property**

3. required long integration
4. required short integration
5. threshold

**Hardware Property:**

Gain jumper sensitivity [mV]  
QDC-Gainjumper used ?

**Output Data**

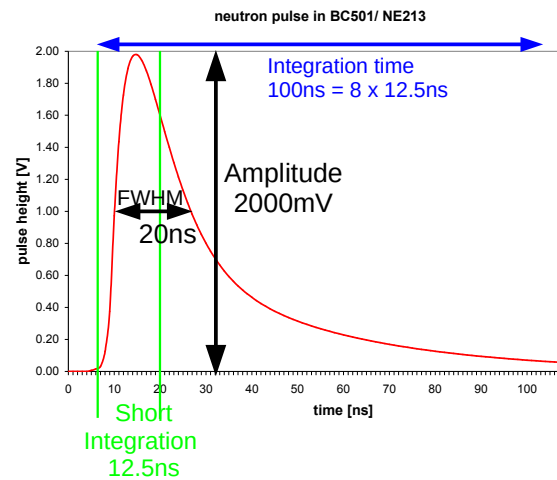
**Amplitude:**

channel 0..15 Amplitude Long int. (16 bit)  
channel 16..31 Amplitude Short int. (16 bit)

**Timing:** Difference to window start:

channel 16 to 31 channel time difference (16bit)  
Chan 32,33 Trigger input 0,1 time diff. (16 bit)

Example: The following diagram shows the



The initialization data for MDPP-16-QDC are:

Signal_width = 20
Input_Amplitude = 2000
Jumper_range = 3000 // for 3V-Jumper
QDC_Jumper = 0 // 0 = standard jumper
Integration_long = 8
Integration_short = 1
threshold0 0x200 // = 1/128 of full range 0xFFFF

**Monitor outputs**

(Lemo 2 = mon 0, and Lemo 3 = mon 1)

Switching on the monitor: press pus button "chan", then select a wave form with "Tmon" button. The button "chan" allows to switch through the individual channels.

As the monitor output has limited bandwidth, the adjustmen parameters (signal width) should be measured by oscillocope.

**Tmon 1:**

Green: mon 0, short integration signal, which is calculated from differentiated signal shown above with a following trpezoidal filter. The first positive maximum is peak sensed and converted.

Magenta: mon 1, long integrated signal. An integral of the differentiated Signal of T0 magenta.

The flicker mark shows the sampling time.

**Wave forms:**

**Tmon 0,**

Green: mon0, signal before ADC,  
Magenta: mon1, differentiated input signal.  
The differentiation time (here it is the distance between positive peak and negative peak) corresponds to the long integration time.



Tmon0, green=inp.,mag.=differentiated

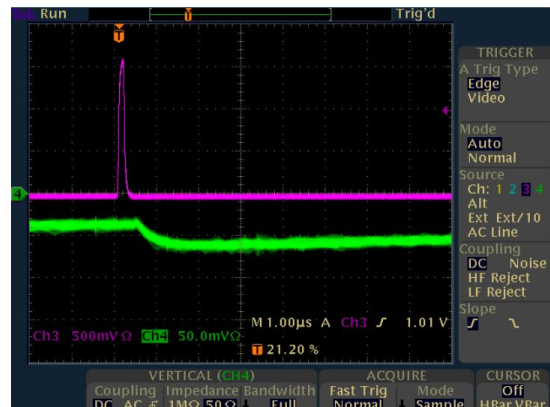


Tmon1, green=Shortint; mag.=Longint

**Tmon 2 :**

Green: mon0, baseline from BLR, multiplied x8.

Magenta: mon 1, Long integration signal, baseline corrected.



Tmon2, green=Baseline, mag. =Longint

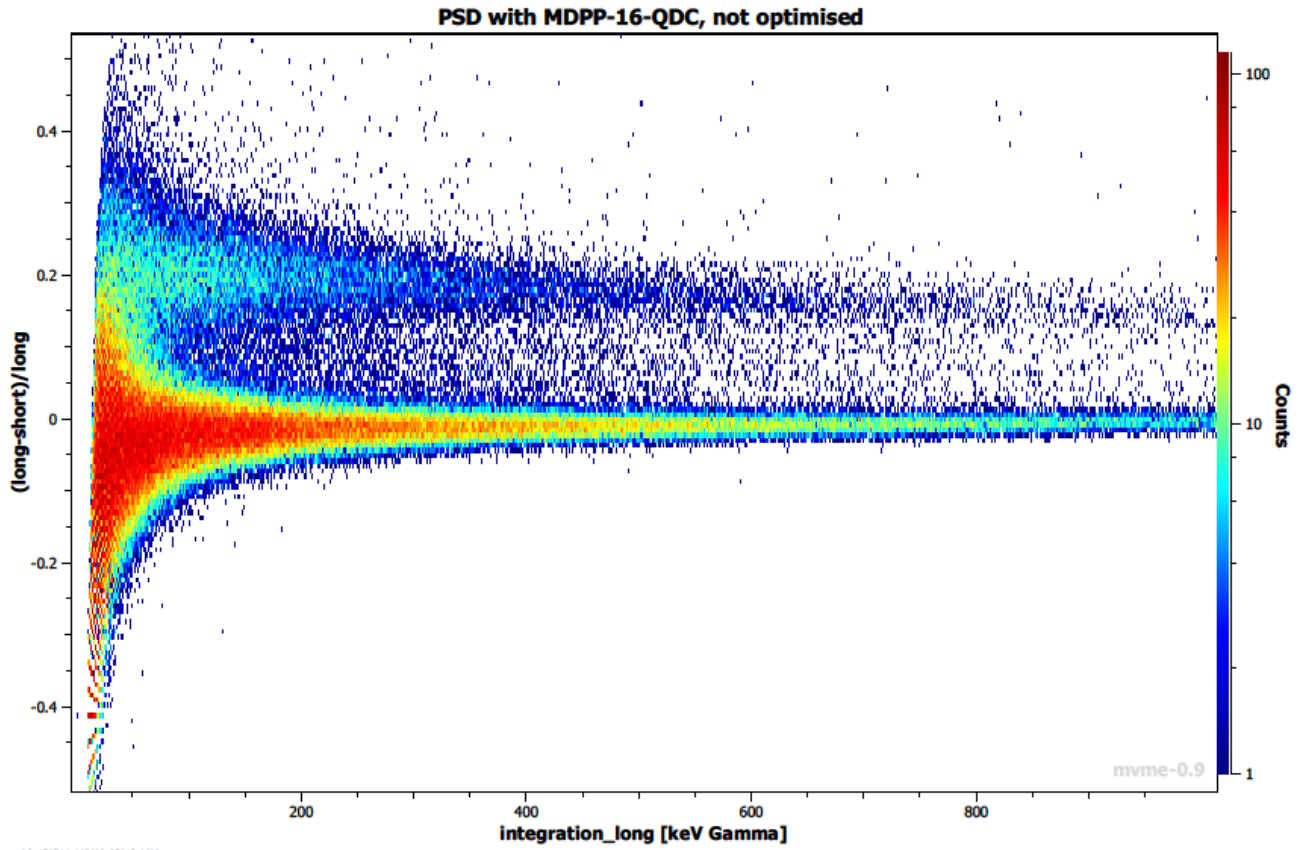
**Tmon 3: Check noise**

Green: mon 0, signal from short shaping, differentiated. Trigger and timing is generated from zero crossing of this signal.

Magenta: mon 1, signal from short shaping, same as Tmon1 green.



Tmon3, green=Z-cross, mag.=TF-out



**MDPP-16 register set, QDC Firmware.**
**Only registers which are different to RCP and SCP software modules are listed.**

Data FIFO, read data at address 0x0000 (access R/W D32, 64)

only even numbers of 32 bit-words will be transmitted. In case of odd number of data words, the last word will be a fill word (= 0).

FIFO size: 48 k - 1k = 48128 words with 32 bit length

**Header (4 byte)**

2 header signature	2 subheader	4	8 module id	3 TDC_resolution → 0x6042	3 ADC_resolution → 0x6046	10 number of following data words, including EOE
b01	b00	xxxx	module id	bxxx	bxxx	number of 32 bit data words

**Data (4 byte) DATA event**

2 data-sig	2	4	2	6	16
b00	01	xxxx	(x, overflow)	channel number 0..15	ADC value long integration

**Data (4 byte) DATA event**

2 data-sig	2	4	2	6	16
b00	01	xxxx	(x, overflow)	channel number 48..63	ADC value short integration

**Data (4 byte) DATA event**

2 data-sig	2	6	6	16
b00	01	xxxxxx	channel number 16..31	TDC time difference

**Data (4 byte) DATA event**

2 data-sig	2	6	6	16
b00	01	xxxxxx	channel number 32, 33	Trigger time difference T0, T1

**Data (4 byte) Extended time stamp**

2 data-sig	2	12	16
b00	10	xxxx xxxx xxxx	16 high bits of time stamp

**Data (4 byte), fill dummy (to fill MBLT64 word at odd data number)**

2	30
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data-sig	
b00	0

**End of Event mark (4 byte)**

2	30
b11	event counter / time stamp



## Registers

	<b>operation mode</b>				
0x6044	output_format	2	RW	3	0 = time and long integral 1 = long_integral only (QDC-mode) 2 = time only (TDC mode) 3= long_integral, short_integral and time
0x6046 <sup>(1)</sup>	adc_resolution <sup>(1)</sup>			4	0 = 64k 1 = 32k 2 = 16k 3 = 8k 4 = 4k (default)

### Channel addressing (select channel which are set)

0x6100	select_chan_pair	4	RW	8	channel to be modified: 0..7 channel pairs; 0 = chan 0,1 1 = chan 2,3 ... 8 = all channels (set to common values)

### Channel settings for pairs of channels,

**\*\*\* After writing a register in this page, 20us wait time is required \*\*\*\*\***

Address	Parameter				
0x6110	Signal_width	10	RW	16	[FWHM, ns],
0x6112	Input_Amplitude	16	RW	1024	[mV], input amplitude 0 to peak in mV
0x6114	Jumper_range	16	RW	3072	[mV], Range printed on jumper top
0x6116	QDC_Jumper	1	RW	0	1= yes, 0=no
0x6118	Integration_long	7	RW	16	[12.5 ns], 2..506 <sup>(1)</sup> in clock steps of 12.5ns
0x611A	Integration_short	5	RW	2	[12.5 ns], 1..127 <sup>(1)</sup> in clock steps of 12.5ns must be < than long integration
0x611C	threshold0	16	RW	0xFF	1...0xFFFF; example: 0.8% = 0x200;
0x611E	threshold1	16	RW	0xFF	1...0xFFFF; for odd channel in pair
0x6128	reset_time	10	RW	32	multiple of 12.5ns; default is usually good
0x612A	long_gain_correction	12	RW	1024	256: divide by 4, 4096 multiply by 4, 1024 neutral;
0x612C	tf_gain_correction	12	RW	1024	
0x612E	short_gain_correction	12	RW	1024	

**Note(1), Firmware from March 2021**

## How to set channel parameters

**Signal\_width** This is the width of the input pulse at half the peak amplitude in ns. The pulse must be measured with a **terminated** oscilloscope. Do not measure at the monitor output of MDPP-16 ! it does not have the band width to properly measure the pulse width;

**Input\_amplitude:** This is the amplitude of the input pulse measured from base line to peak in mV. Offsets of the signal have no effect. The pulse must be measured with a terminated oscilloscope. Do not measure at the monitor output of MDPP-16 ! it does not have the band width to properly measure the pulse width;

**Jumper range:** The value is printed on the jumper. multiply the value by 1000 to get the mV unit.

**QDC\_Jumper:** set 1 if you used a QDC-Jumper; This is printed on the jumper. QDC jumpers give better amplitude resolution and linearity if the signal width is less than 15ns. The QDC jumpers have a band width limit of 30MHz, so increase the width of input pulses to about 25ns. They should not be used for pulse shape discrimination.

**Integration\_long:** is the integration time to get the full charge of the input pulse. It is specified in multiples of internal clocks, so 12.5ns. Allowed range is 2 (25ns) to 127 (1.6us)

**Integration\_short:** is the integration time to get the first fast part of the input pulse. It is specified in multiples of internal clocks, so 12.5ns. Allowed range is 1 (12.5ns) to 31 (387ns) It must be smaller than the long integration time.

**Threshold0/1:** The threshold parameter can be set separately for the two addressed channels. Full range is 64k (65535) = 0xFFFF; So a 1% of full range threshold is 65535/100 = 655;

**reset:** At overflow and underflow the input preamplifier and digital section is resetted. The default time is usually good.

**Gain\_corrections:** The internal gains and hardware gain are calculated based on the signal width and amplitude. This should give a quite good start value. Details of the signals will have an effect on the real amplitude. So there are 3 scaling factors to correct the gains. The default of 1024 is the neutral setting, a lower value decreases the amplitude in a spectrum, a higher one increases it. It is possible to decrease the gain by a factor of 4 (->256), or increase it by a factor of 4 (-> 4096).